

Disaster Damage Detection



Disaster Damage Detection



UNIVERSITY of WASHINGTON

eScience Institute

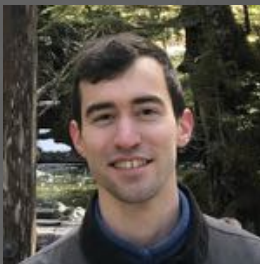
DATA SCIENCE FOR SOCIAL GOOD



Sean Chen



Andrew Escay



Chris Haberland



Tessa Schneider



An Yan



Valentina
Staneva

Data Scientist



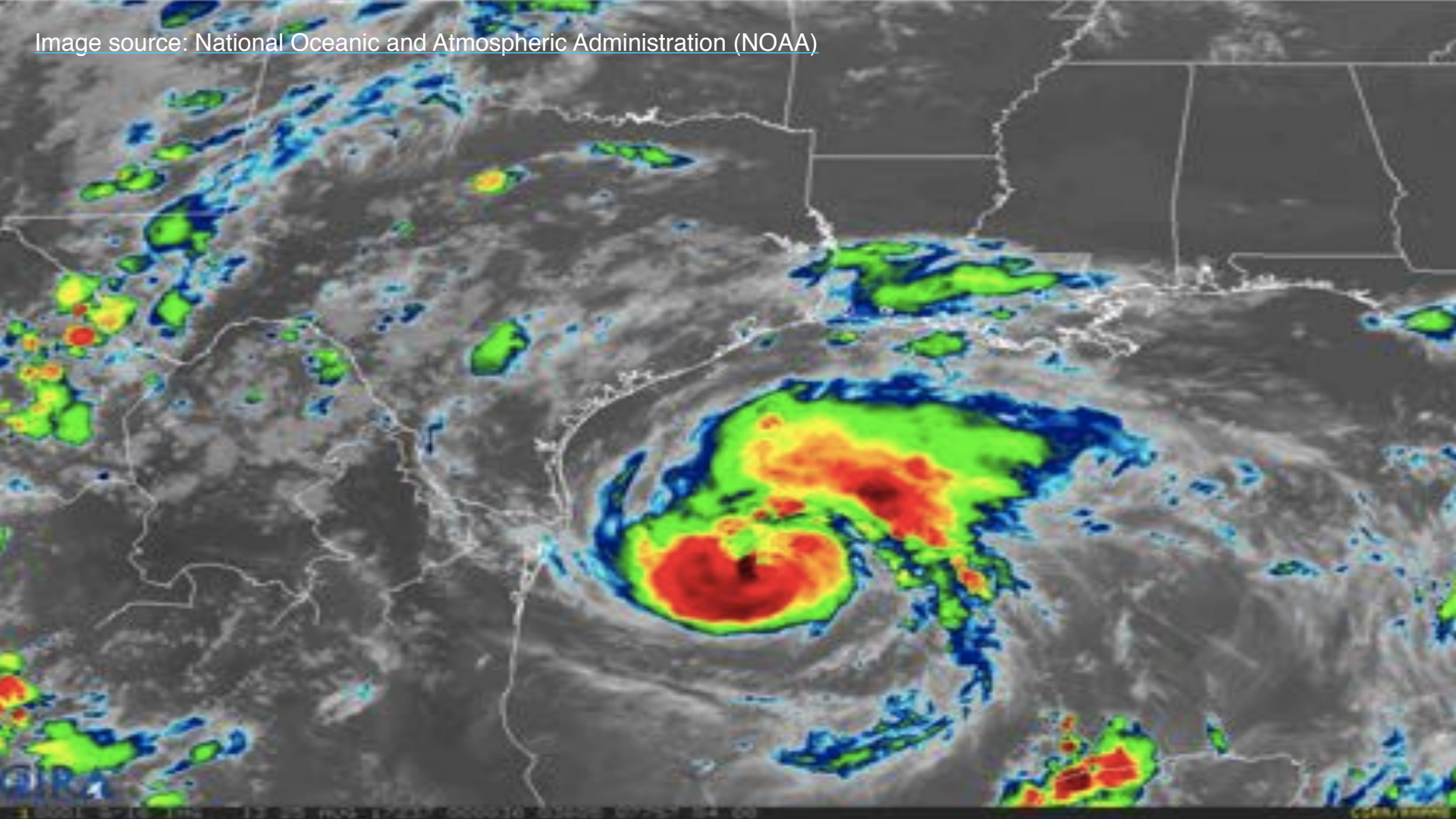
Youngjun
Choe

Project Lead

DSSG Fellows



Image source: [National Oceanic and Atmospheric Administration \(NOAA\)](#)





The Problem

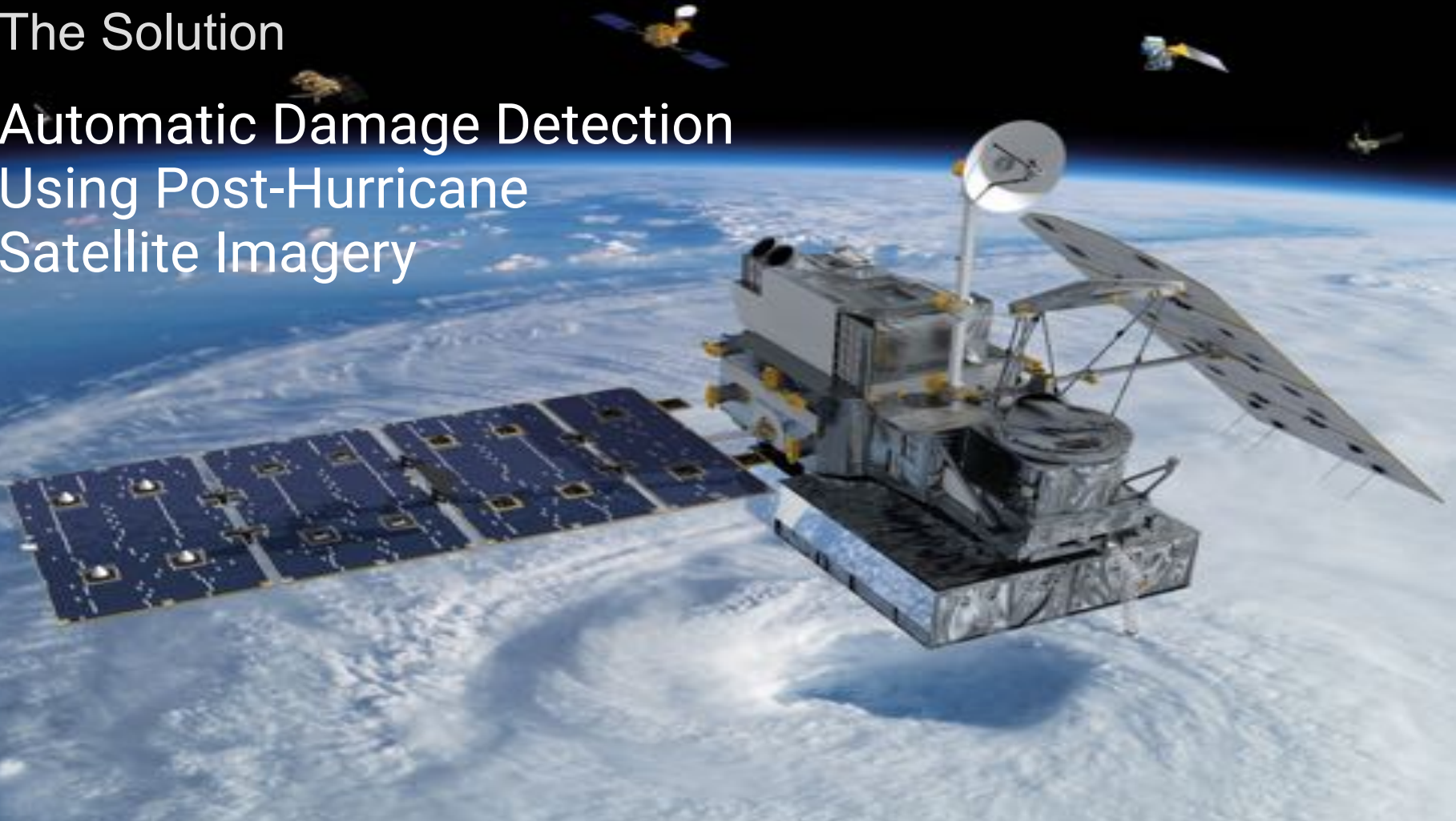


The Problem

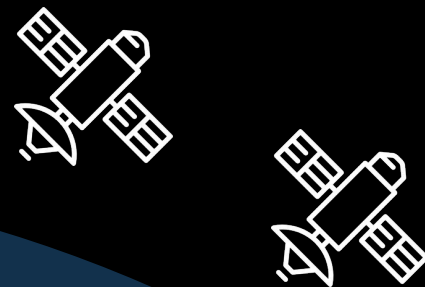
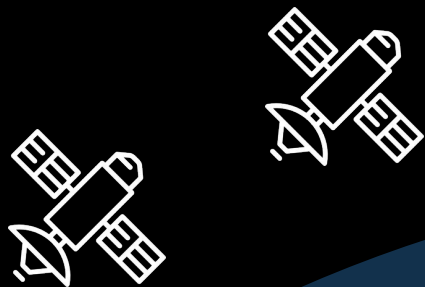


The Solution

Automatic Damage Detection
Using Post-Hurricane
Satellite Imagery



Satellite: High-Level



Aerial: Intermediate-Level



Traditional: Ground-Level





**Creating
Training Data**



**Model
Selection**



**Model
Implementation**



**Model
Results**



**Creating
Training Data**



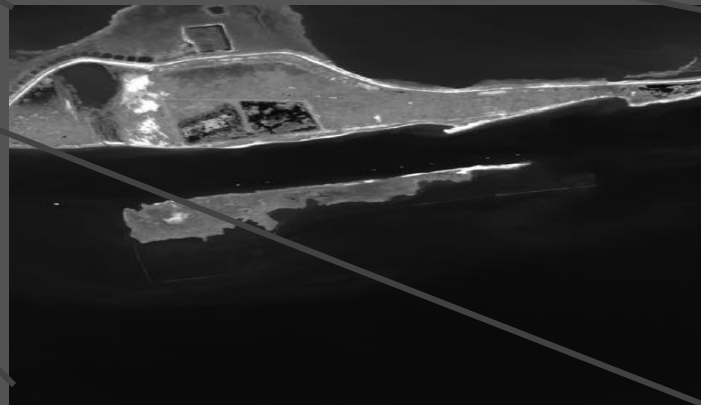
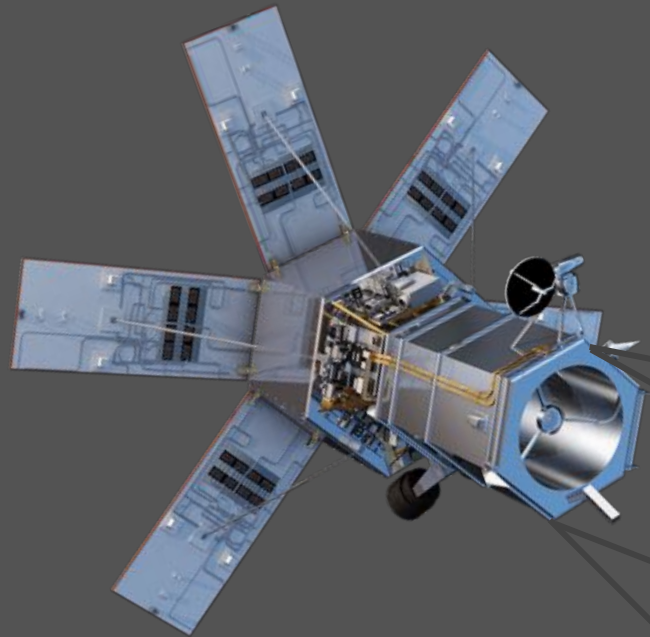
**Model
Selection**

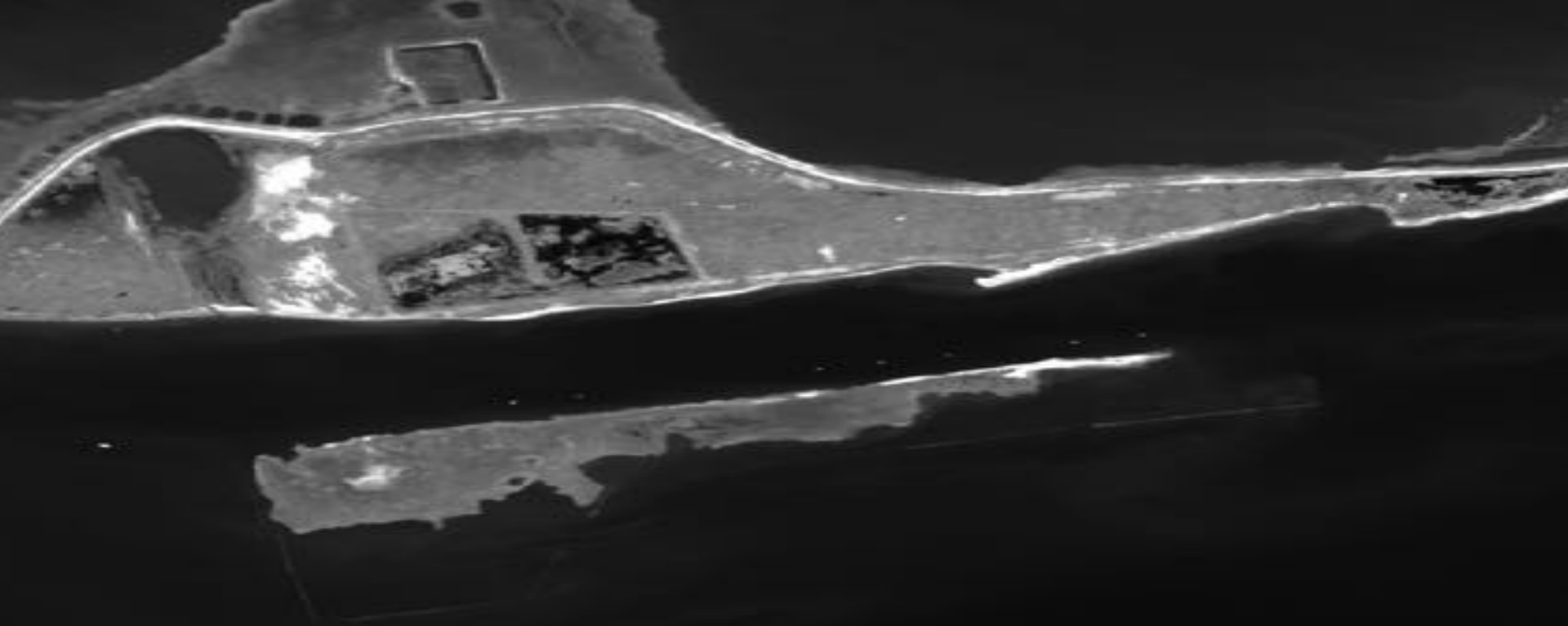


**Model
Implementation**

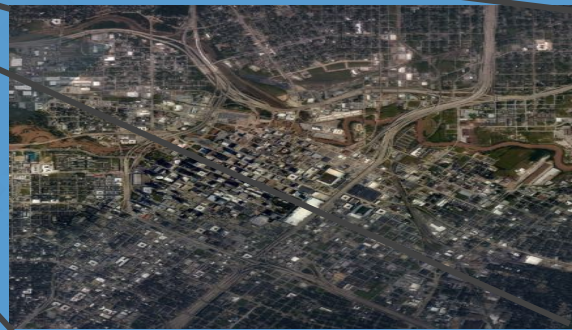


**Model
Results**





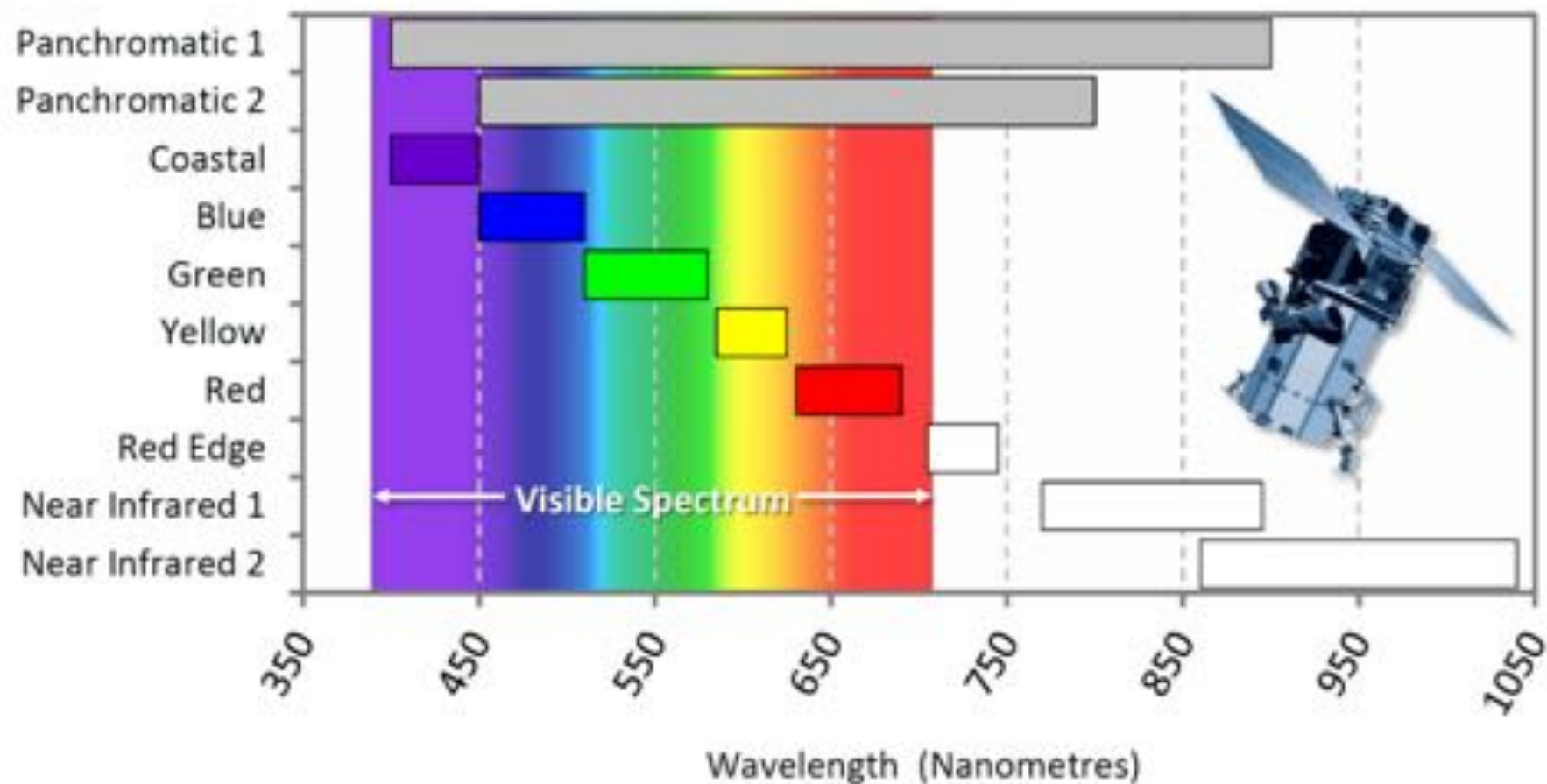
Digital Globe

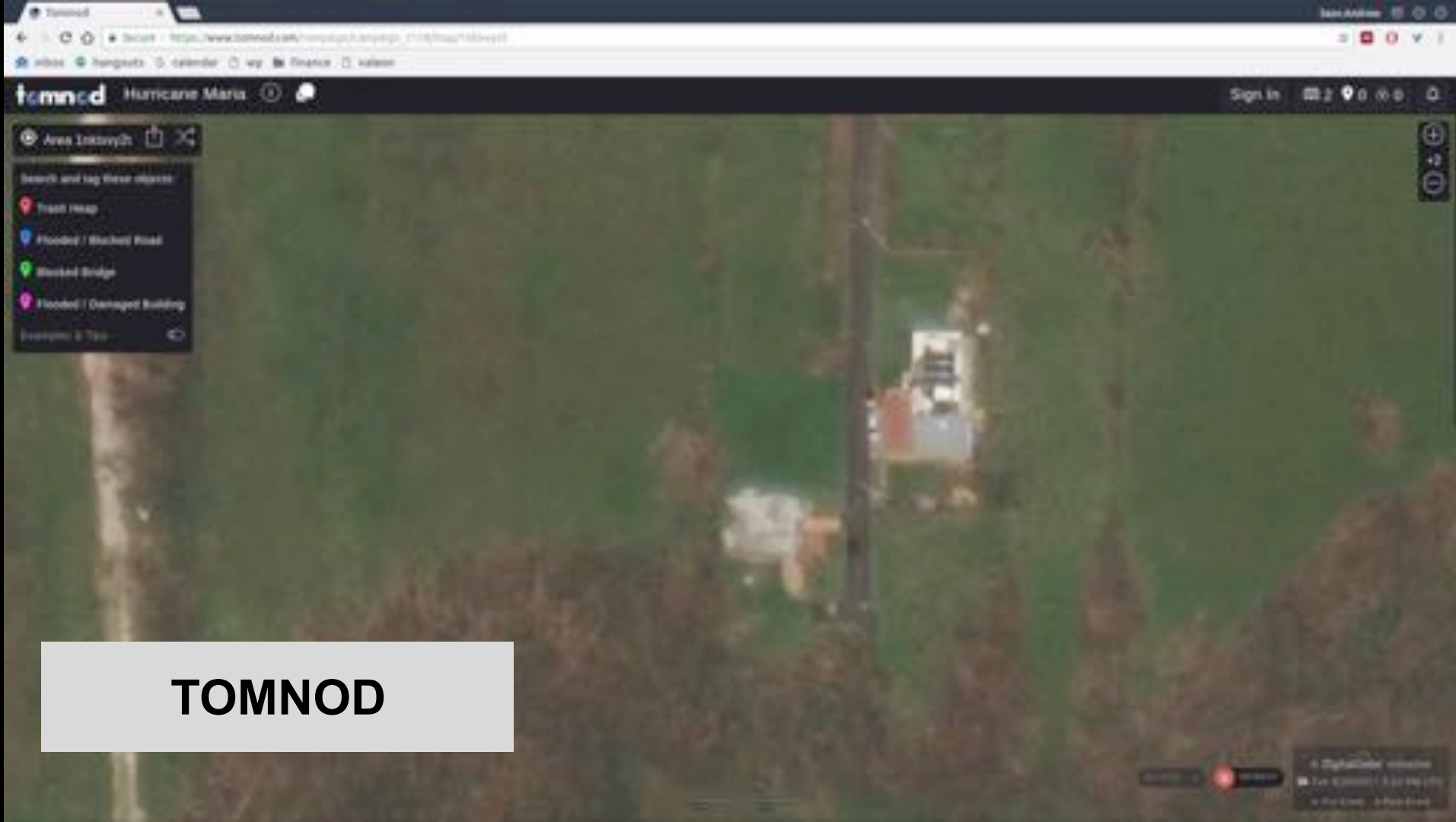




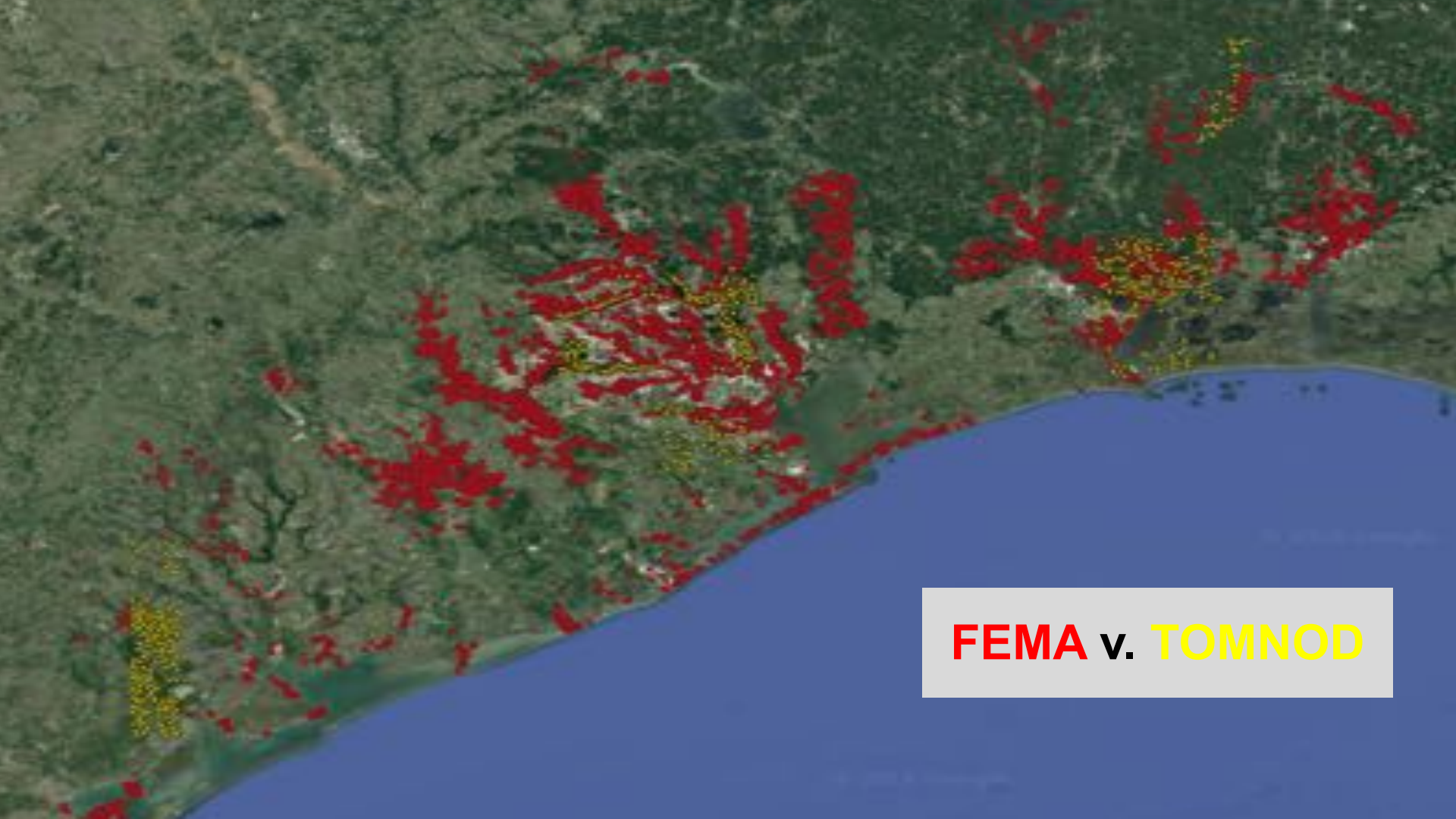
NOAA

WorldView-2 Spectral Bands





TOMNOD



FEMA v. **TOMNOD**



Oak Ridge National Labs



Microsoft



Creating
Training Data



Model
Selection



Model
Implementation



Model
Results

Computer Vision Tasks

Classification

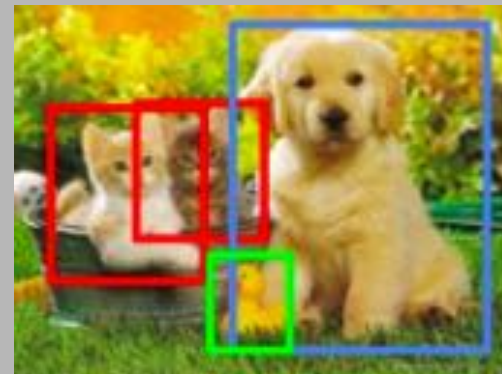


Single object

Segmentation



Object Detection



Multiple objects

Computer Vision with Satellite Imagery

Classification

Building y/n



DigitalGlobe Hurricane Harvey satellite imagery

Segmentation

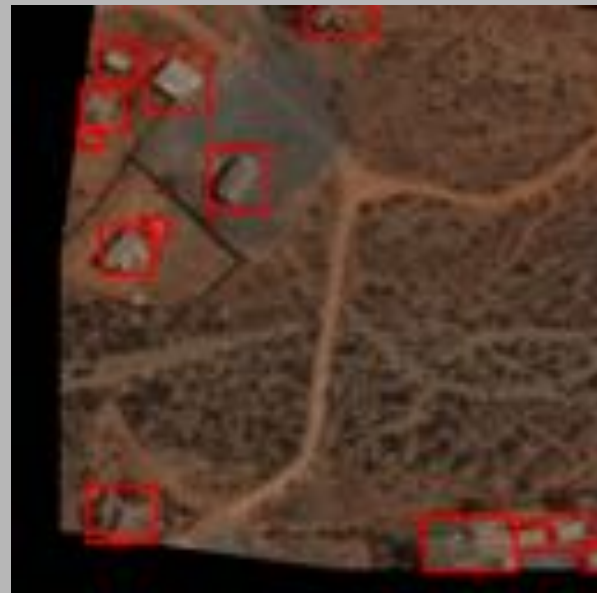
Flooded Roads vs. Background



<https://devblogs.nvidia.com/solving-spacenet-road-detection-challenge-deep-learning/>

Object Detection

Buildings with Bounding Boxes



<https://medium.com/@dariusl/object-detection-baselines-in-overhead-imagery-with-diux-xview-c39b1852f24f>

Object Detection

- Faster R-CNN (Ren et al., 2015)
- Single Shot MultiBox Detector (SSD) (Liu et al., 2016)

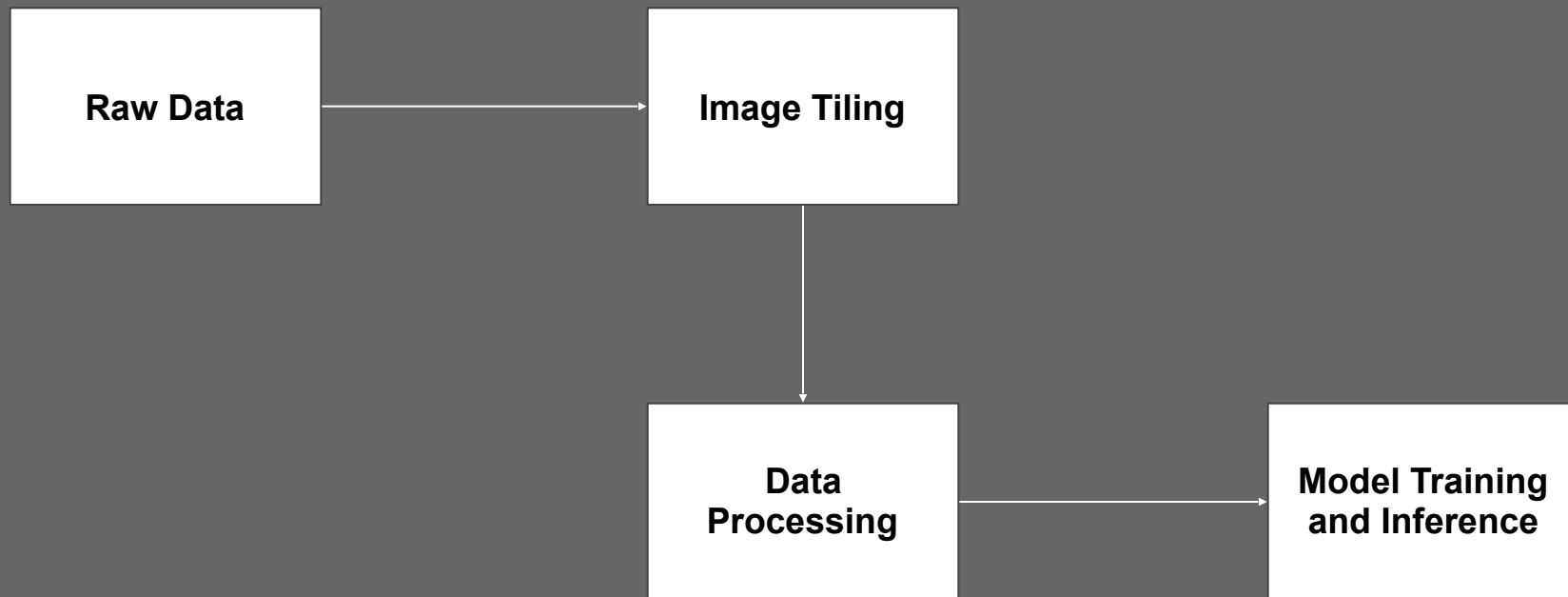


TOMNOD damage predictions with SSD



NOAA damage predictions with SSD

Pipeline





Creating
Training Data



Model
Selection



Model
Implementation



Model
Results

Data

- Satellite Imagery / Aerial Imagery
- Bounding boxes with labels
- Input size: 200 x 200

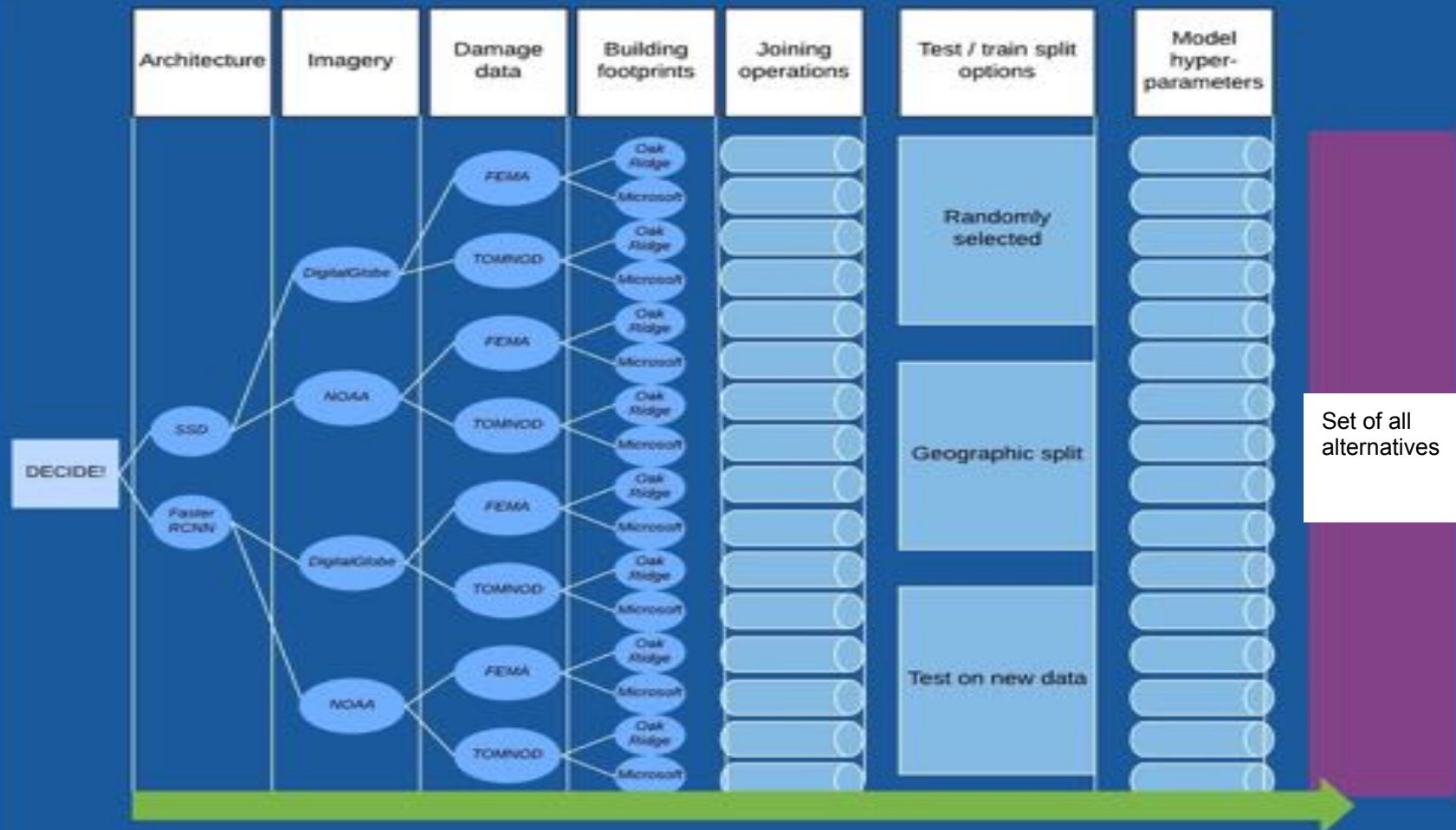
Data Augmentation

- Translation
- Rotation
- Blur
- Zoom In
- Zoom Out
- Flip
- ...

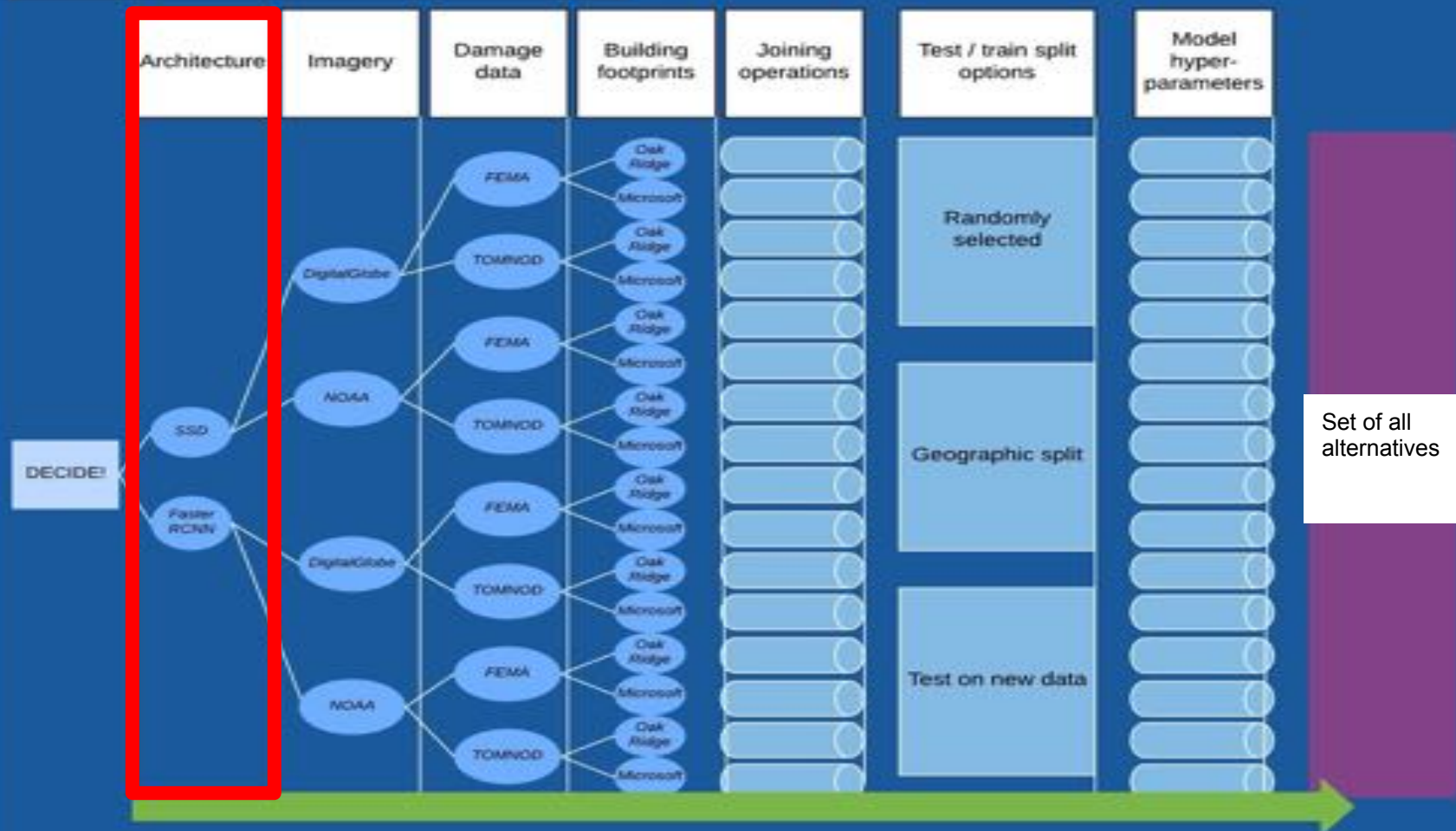
Platform

- GPU: Tesla K80 on AWS
- Implementation: Tensorflow

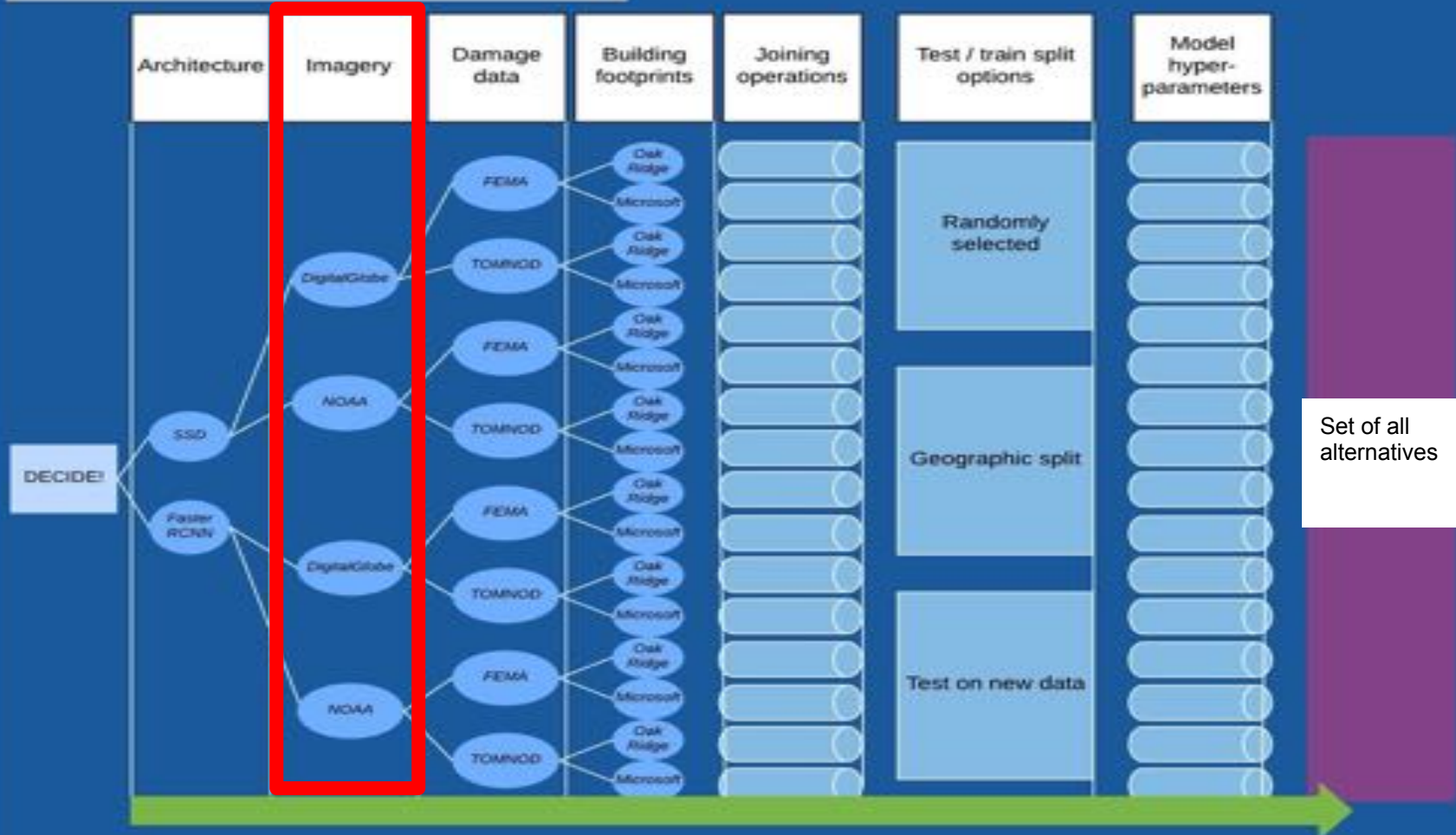
Alternatives



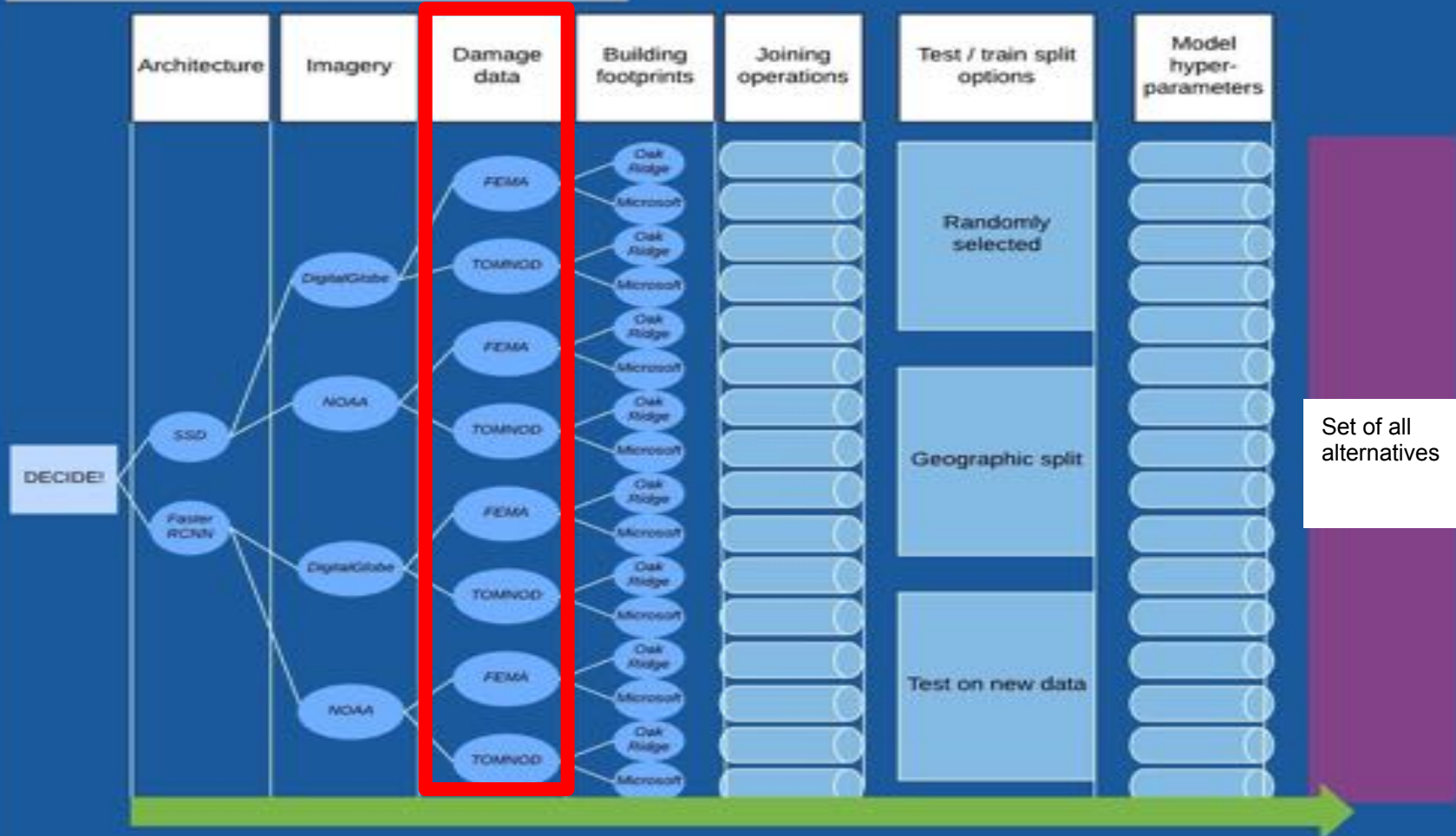
Alternatives



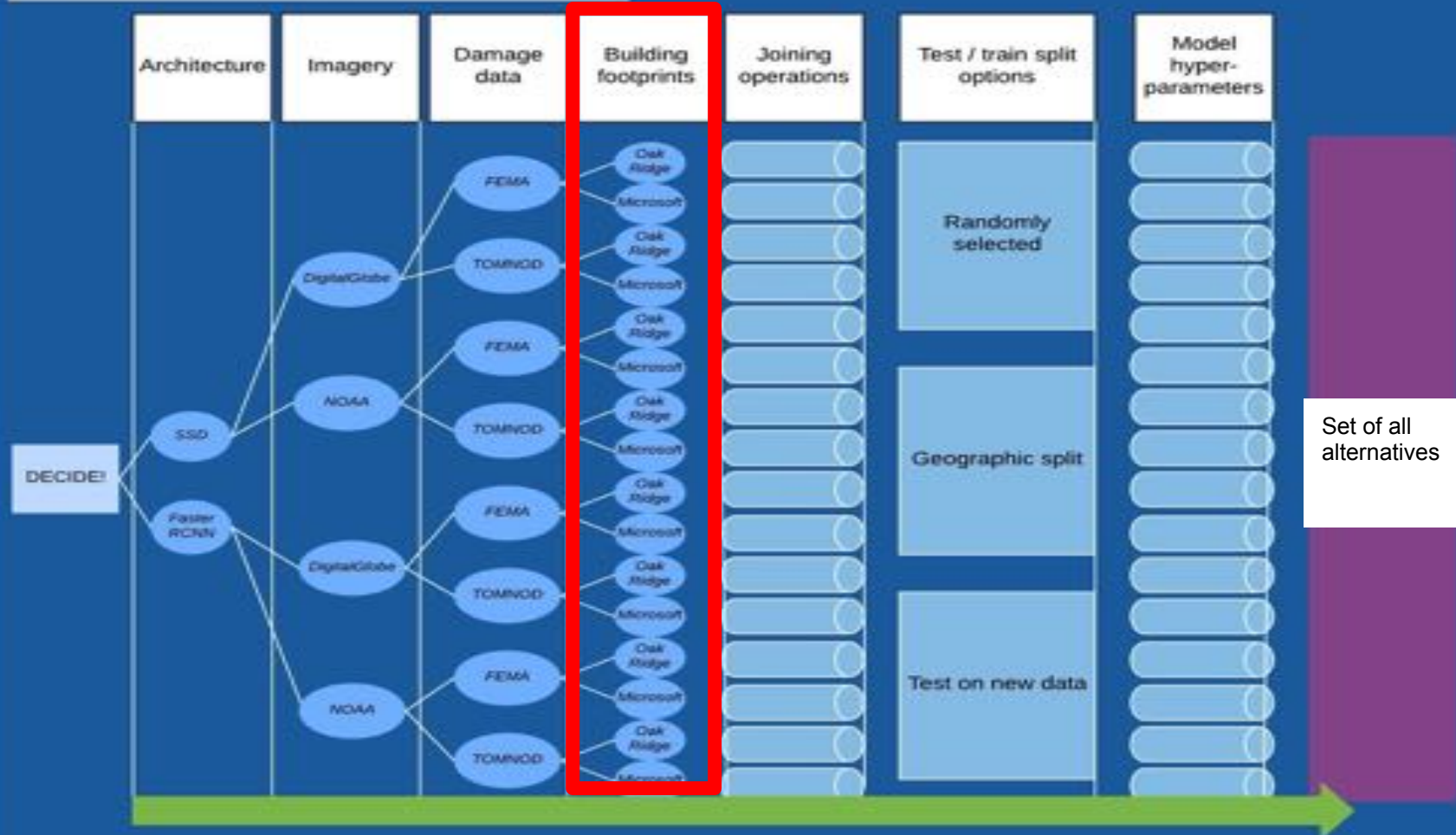
Alternatives



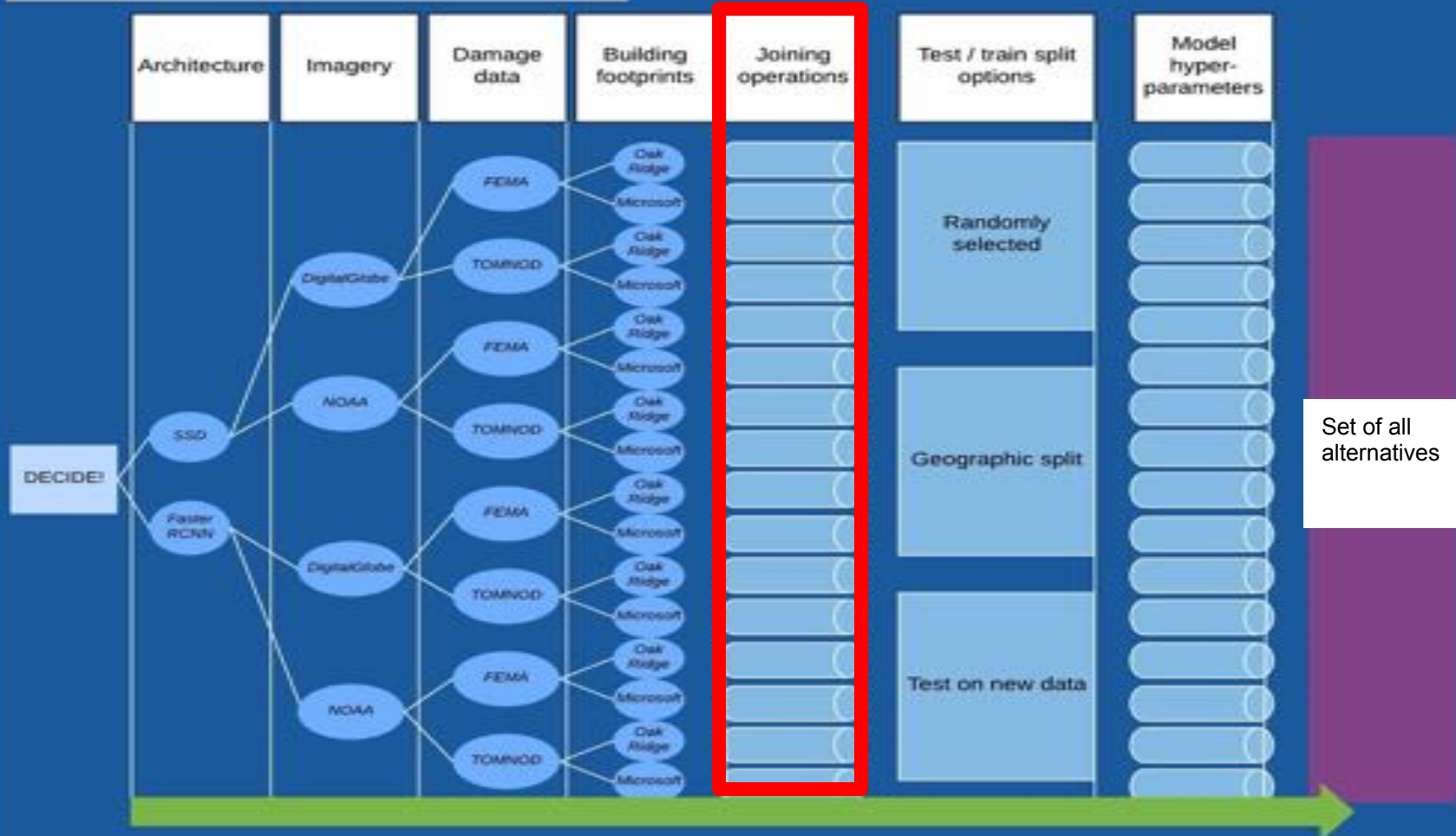
Alternatives



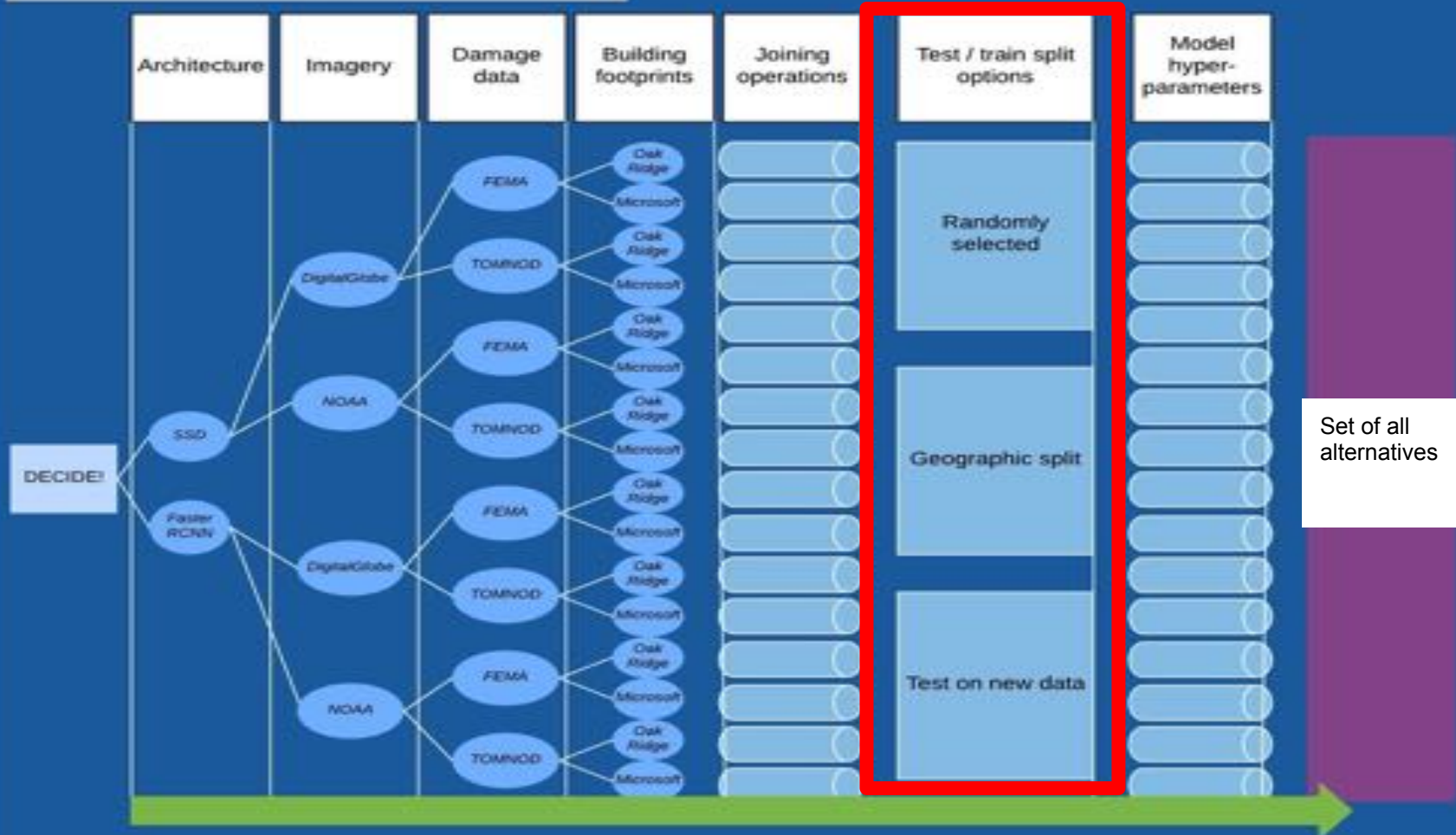
Alternatives



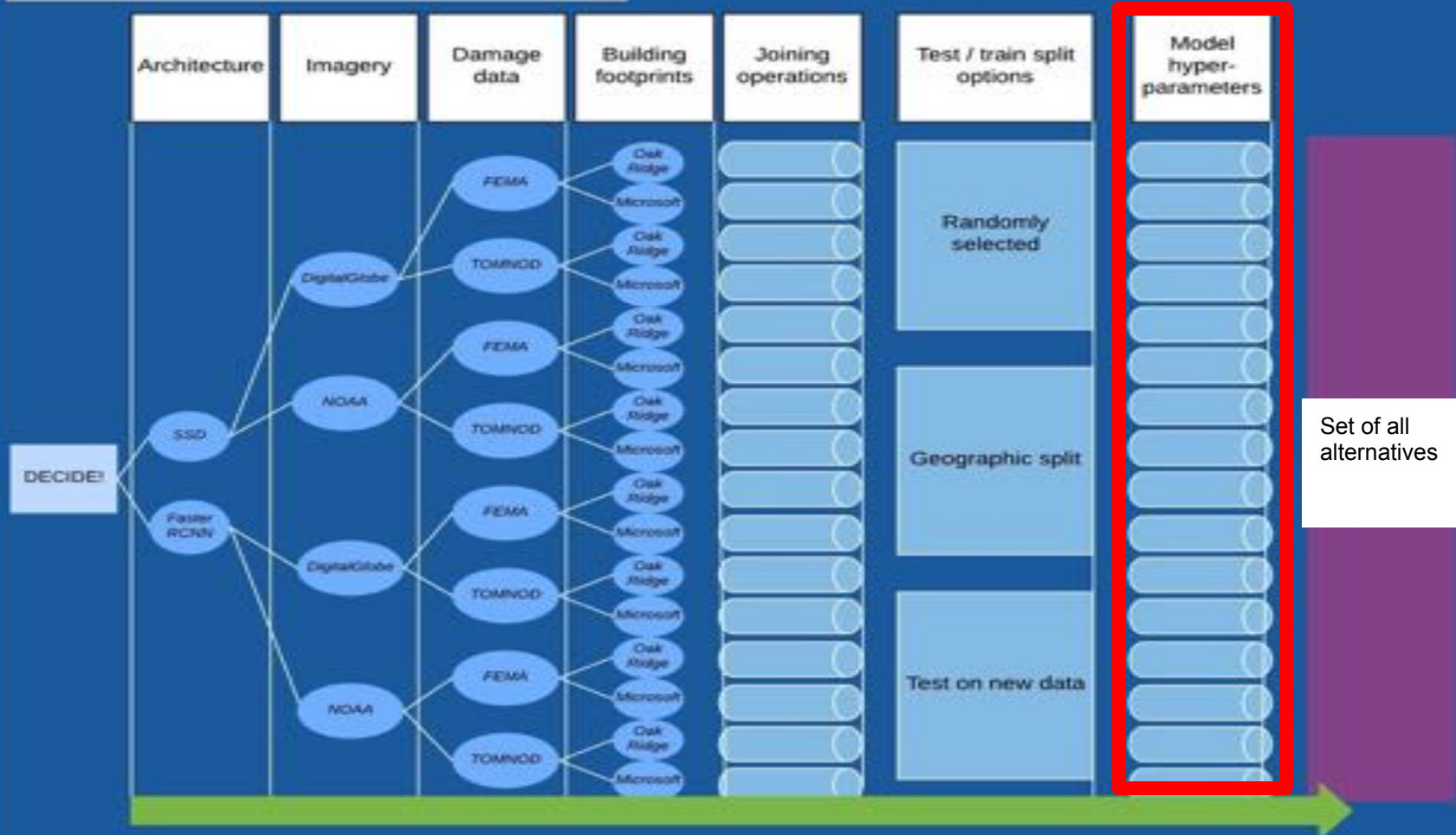
Alternatives






Alternatives



Alternatives



Run Alternatives

	Detection Algorithm	Imagery data	Damage data	Building footprints	Train/Test Split
 1	SSD	Satellite (DigitalGlobe)	Annotated points (TOMNOD)	Joined dataset (Microsoft, Oak Ridge)	Random selection within same geographic area
 2	SSD	Aerial (NOAA)	Parcel-based assessment (FEMA)	Microsoft building footprints	Random selection within same geographic area
 3	Faster R-CNN	Satellite (DigitalGlobe)	Annotated points (TOMNOD)	Joined dataset (Microsoft, Oak Ridge)	Random selection within same geographic area



Creating
Training Data



Model
Selection



Model
Implementation

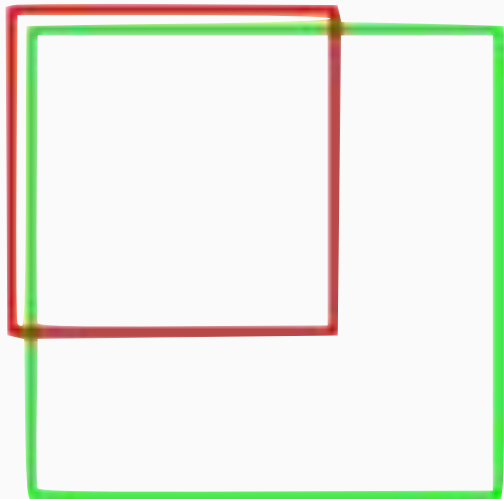


Model
Results

Evaluation: IoU (Intersection over Union)

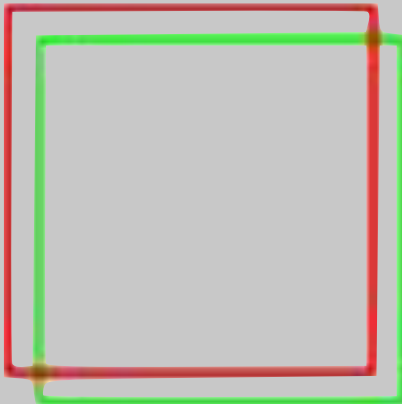
POOR

IoU: 0.4034



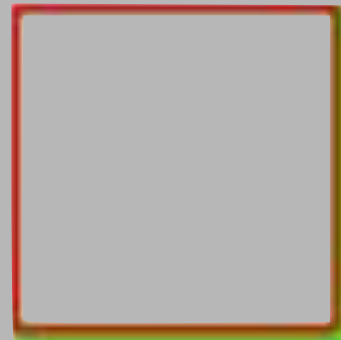
GOOD

IoU: 0.7330



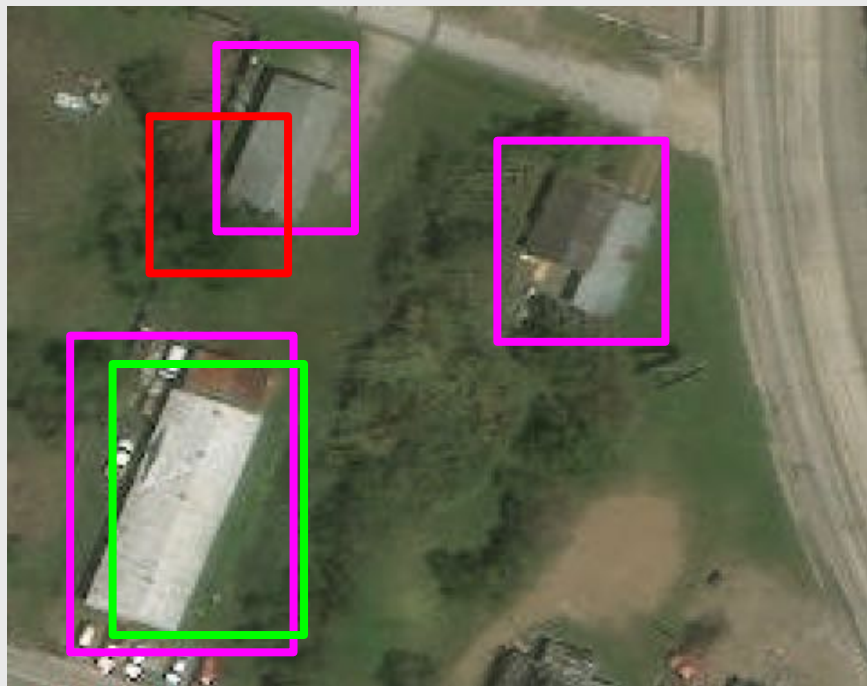
EXCELLENT


IoU: 0.9264




Evaluation

IoU (Intersection over Union) at .5

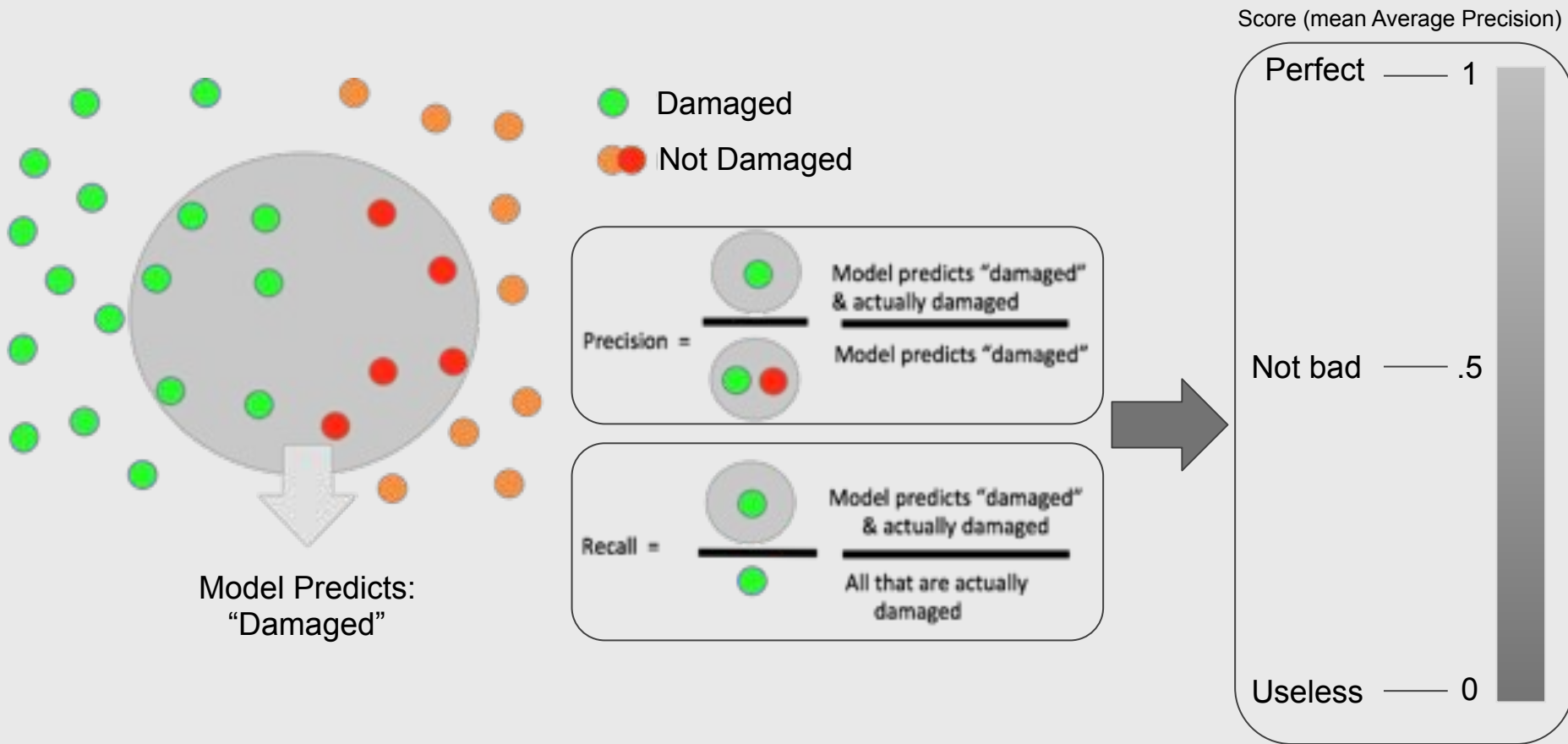


 — Human-labeled box

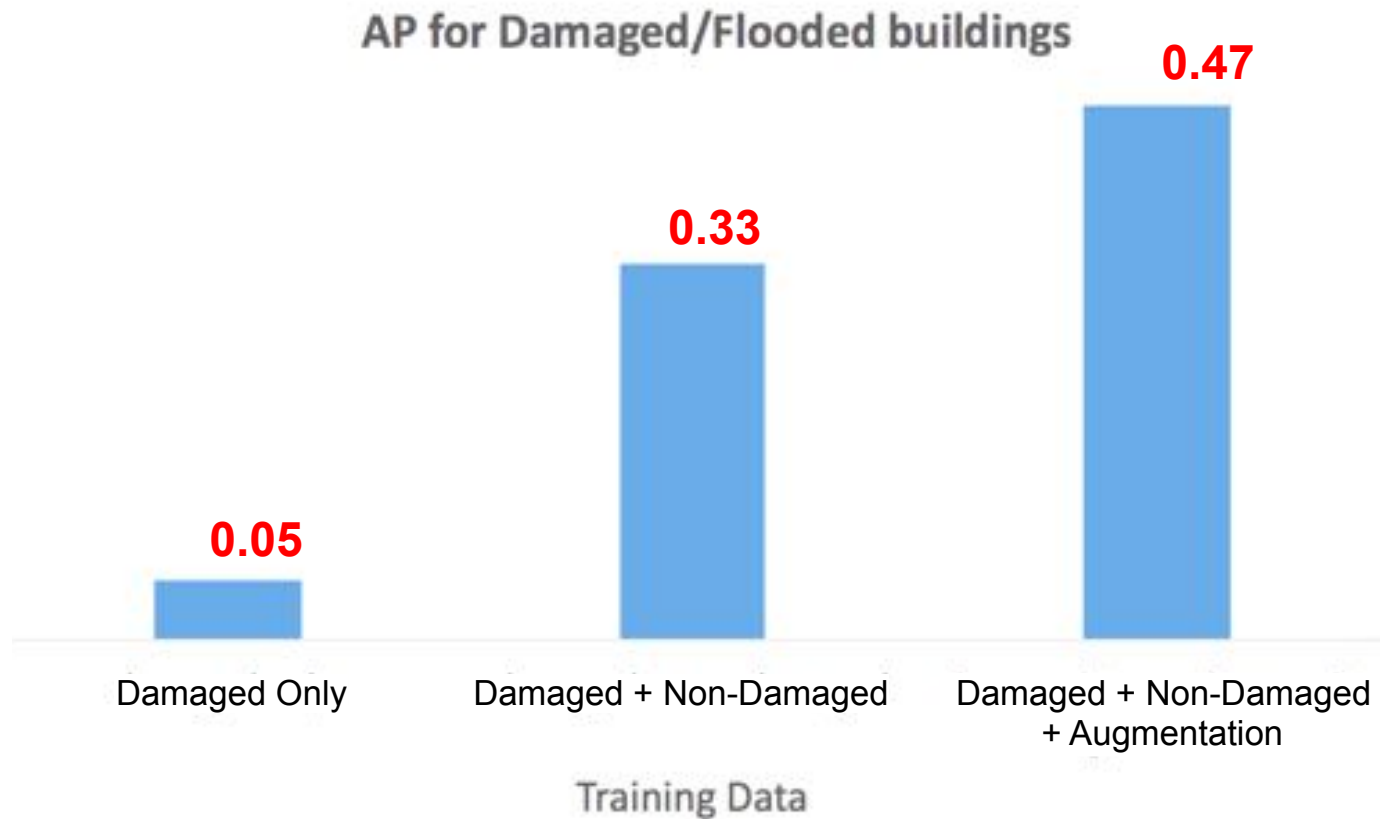
 — Model “yes”, TRUE

 — Model “yes”, FALSE

Evaluation: Scoring



Results



Results

Alternative	Flooded/Damaged	Non-damaged	Evaluation Score (mAP)
SSD on Satellite Imagery	0.47	0.62	0.55
SSD on Aerial Imagery	0.32	0.65	0.48
Faster R-CNN Satellite Imagery	0.31	0.61	0.46

Human-labeled data



Predicted output



Identify Flooded Buildings

Evaluation

Human-labeled data



Predicted output



Identify Flooded Buildings

Evaluation

Human-labeled data



Predicted output



Identify Damaged Buildings (Blue Tarp)

Evaluation

Human-labeled data



Predicted output



Identify Damaged Buildings



**Creating
Training Data**



**Model
Selection**



**Model
Implementation**



**Model
Results**



Creating
Training Data



Model
Selection



Model
Implementation



Model
Results



[https://dds-lab.github.io/
disaster-damage-detection/](https://dds-lab.github.io/disaster-damage-detection/)



Disaster Damage Detection



GORDON AND BETTY
MOORE
FOUNDATION



UNIVERSITY of WASHINGTON
eScience Institute






Urban@UW

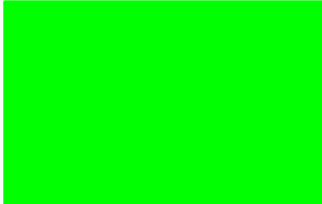
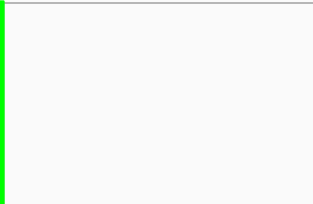
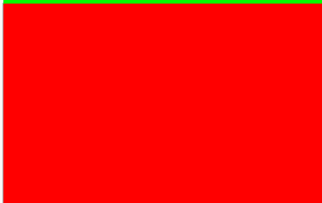

CASCADIA URBAN
ANALYTICS COOPERATIVE

Questions

Evaluation



-  — Human-labeled box
-  — Model prediction
-  — True positive count
-  — False positive count
-  — False negative count

		Model prediction	
		Positive	Negative
Actual	TRUE!!!!		
	FALSE...		

Precision and Recall

$$\text{Recall} = \frac{\text{True Positive}}{\text{True Positive} + \text{False Negative}}$$

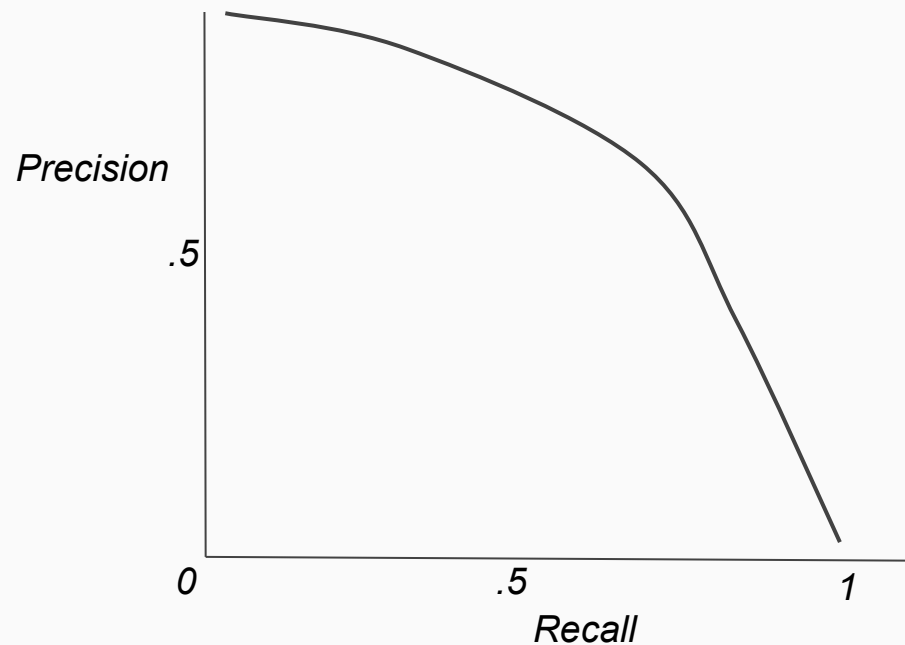
$$\text{Precision} = \frac{\text{True Positive}}{\text{True Positive} + \text{False Positive}}$$

		Prediction	
		Positive	Negative
TRUE!!!!			
FALSE...			

Precision and Recall

$$\text{Recall} = \frac{\text{Green}}{\text{Green} + \text{Orange}}$$

$$\text{Precision} = \frac{\text{Green}}{\text{Green} + \text{Red}}$$

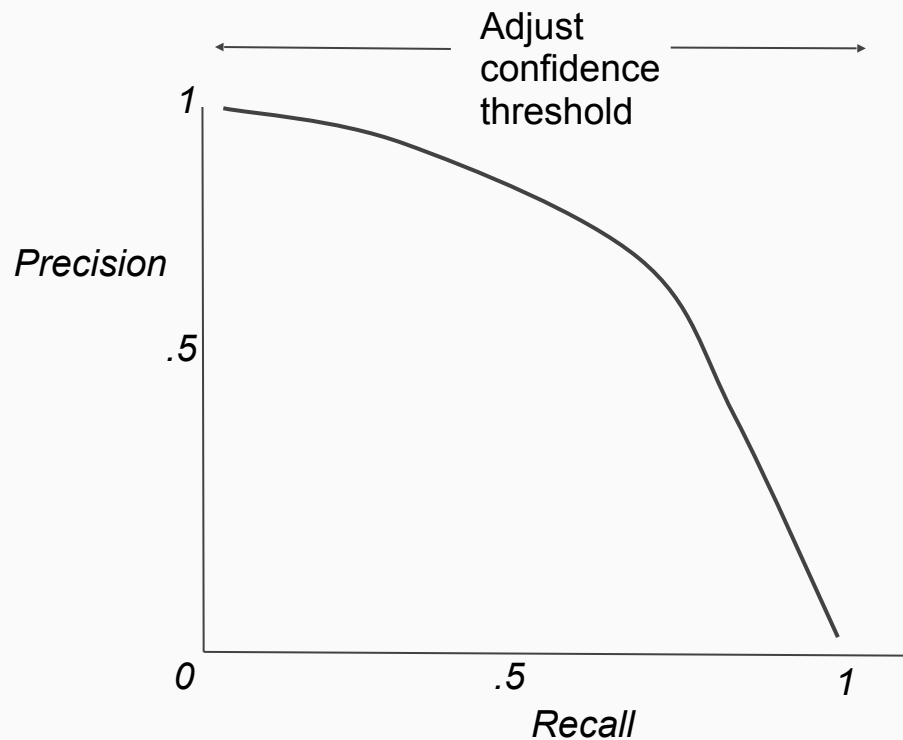


Evaluation

Precision and Recall

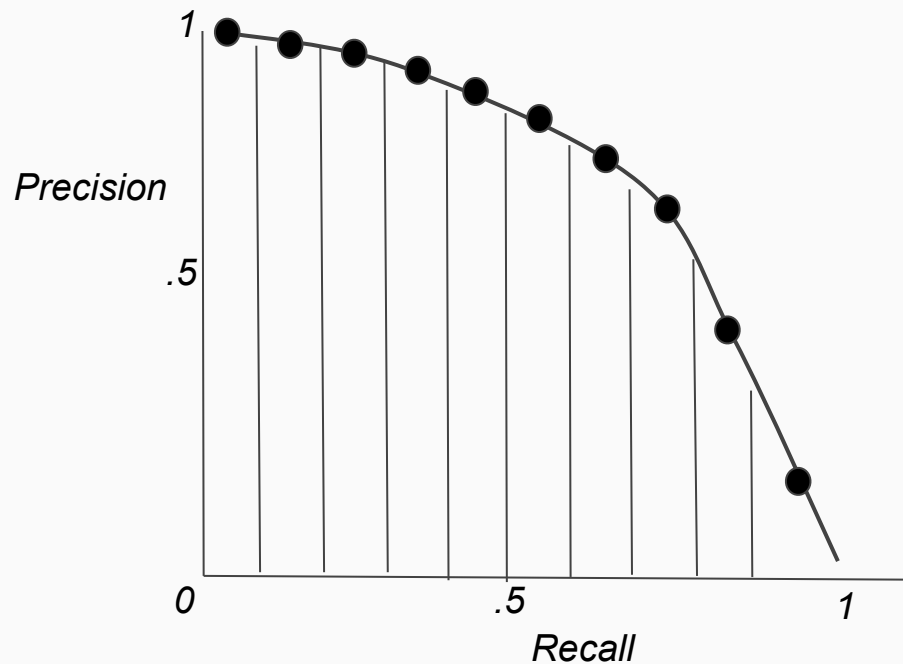
$$\text{Recall} = \frac{\text{Green}}{\text{Green} + \text{Orange}}$$

$$\text{Precision} = \frac{\text{Green}}{\text{Green} + \text{Red}}$$



Precision and Recall

Average Precision (AP) = Average precision across evenly divided points on the curve

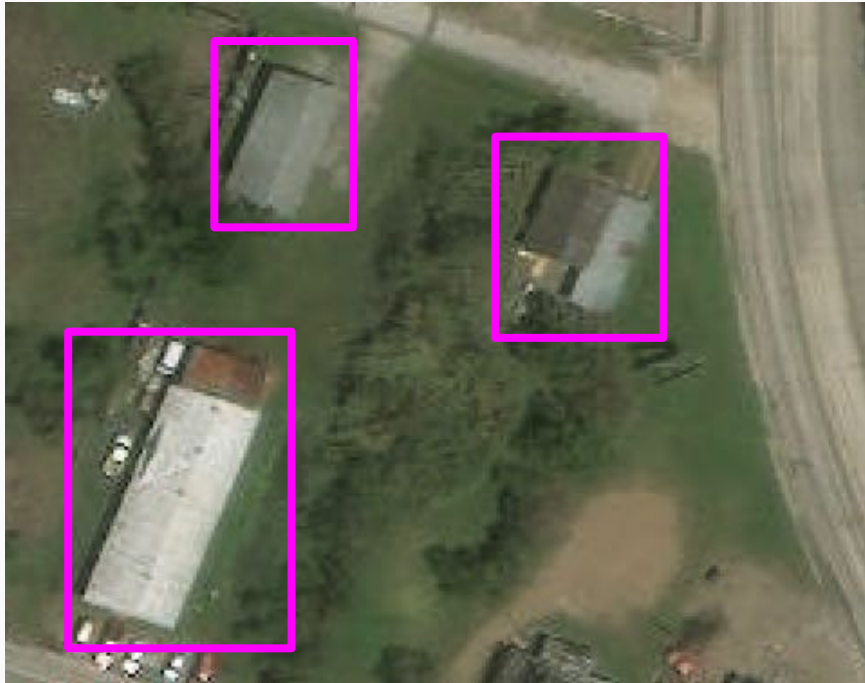


Mean Average Precision

Mean Average Precision (mAP) = mean of AP for each class (damaged and non-damaged)

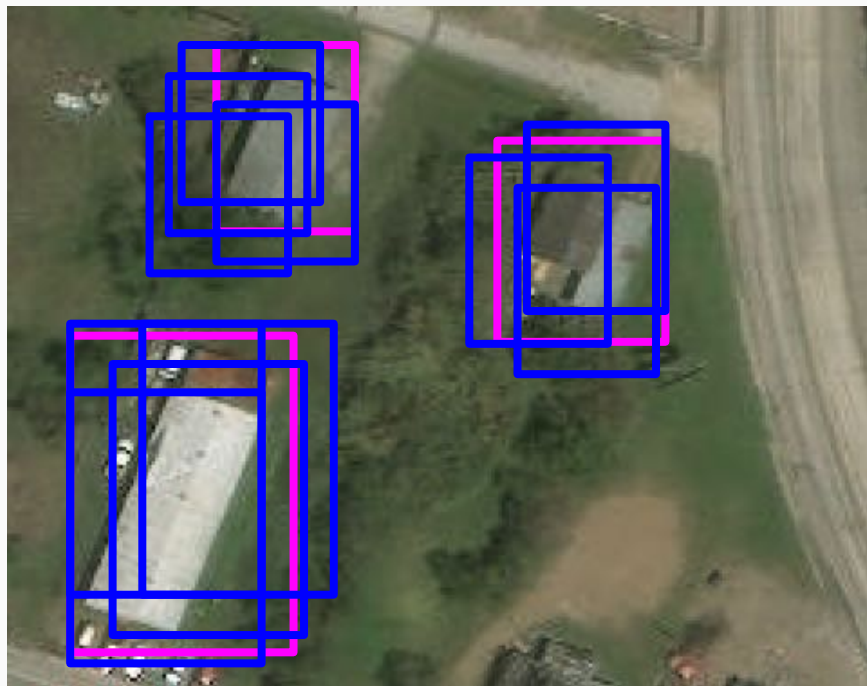
$$\frac{AP_{\text{damage}} + AP_{\text{non-damaged}}}{2}$$



Evaluation



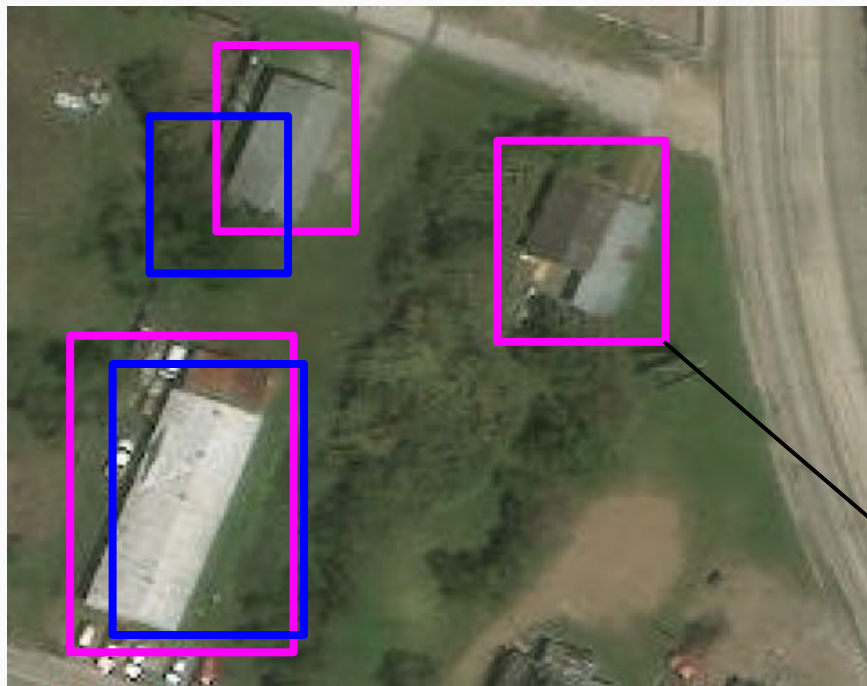
 — Human-labeled box

Non-max suppression at IoU at .5



-  — Human-labeled box
-  — Model prediction

Non-max suppression at IoU at .5



— Human-labeled box

— Model prediction

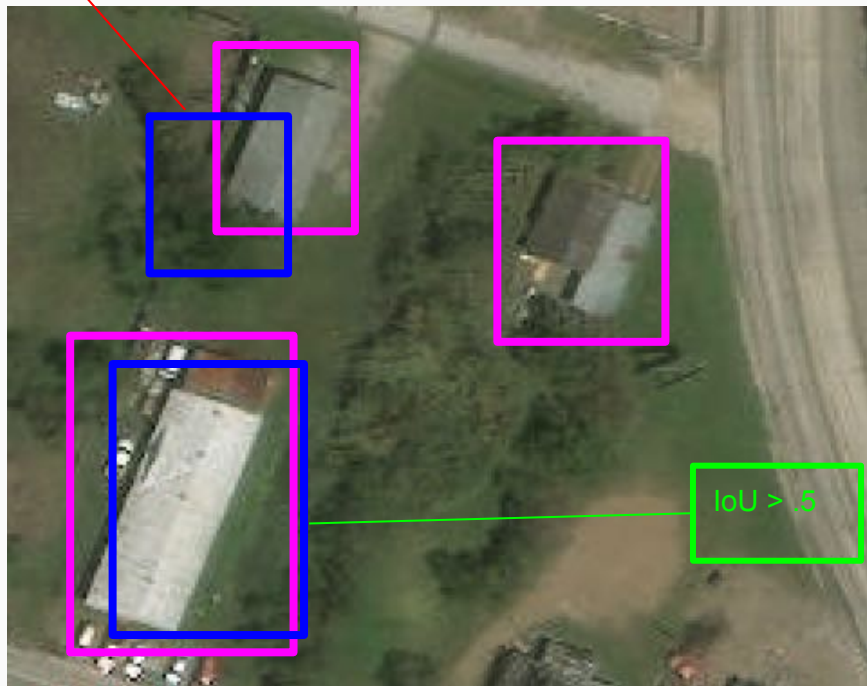
Highest-confidence box out of overlapping boxes remains

No predicted box with high confidence here

Evaluation

Non-max suppression at IoU at .5

$\text{IoU} < .5$



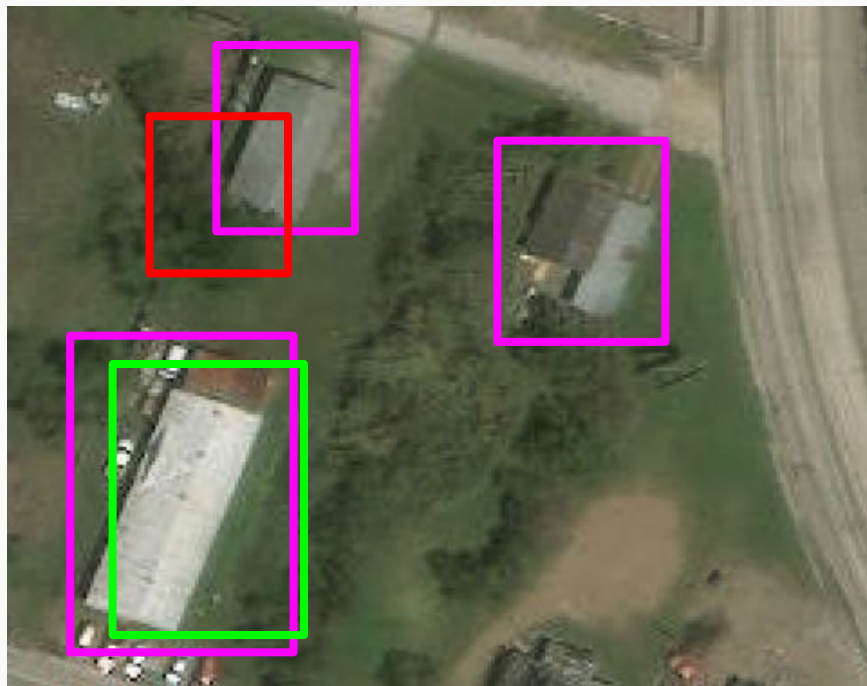
— Human-labeled box


— Model prediction

— Model “yes”, TRUE


— Model “yes”, FALSE

IoU (Intersection over Union) at .5



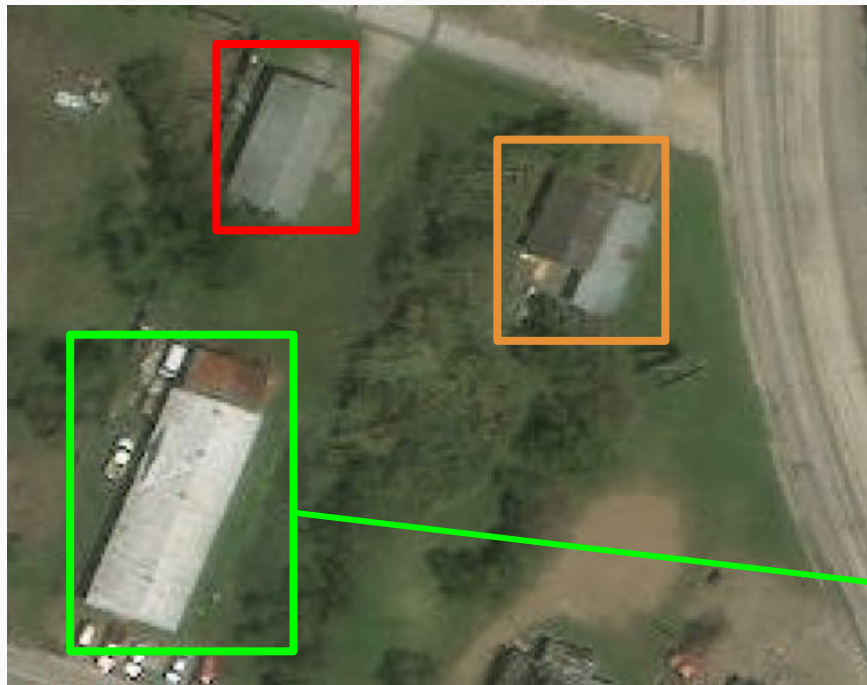
 — Human-labeled box


 — Model prediction


 — Model “yes”, TRUE

 — Model “yes”, FALSE

Scoring



 — Human-labeled box

 — Model prediction

 — Model “yes”, TRUE

 — Model “yes”, FALSE

 — Model “no”, FALSE

Counts as “correctly” predicted